

# PROCESS, PLANT AND MACHINE SAFETY



# SAFETY @ STEMS

# **CHEMICAL SAFETY**



# **MACHINERY SAFETY**



#### **RISK ASSESSMENT**



#### **REFERENCE CONTEXT**



# SAFETY @ STEMS

# CHEMICAL SAFETY

Risk prevention and mitigation associated with

- Explosions
- Fires
- Release of toxic substances

# **MACHINERY SAFETY**

Need to guarantee

- Performance functional to safety for the operator
- Reliability
- ... in a context more difficult
  - ✓ Smart/autonomous robots and systems
  - ✓ Higher complexity of electronic control systems (especially in new electrified vehicles)
  - ✓ More stringent requirements with respect to noise and vibrations

# **RISK ASSESSMENT**

Reduction of forest fire risk

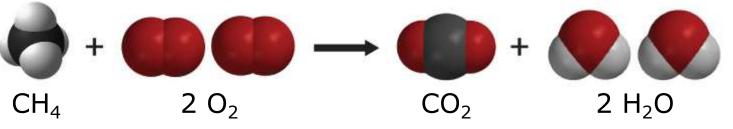
- ✓ Extreme climatic conditions (drought)
- ✓ Forest fires also close to urban / industrial areas

# **REFERENCE CONTEXT**



Development of prototypes and experimental protocols and methodologies and predictive mathematical models for the analysis, prevention and mitigation of risks associated with accidental phenomena, such as explosions, fires and the release of toxic substances

from "FUNDAMENTALS" ...



**Chemical reaction** → **Turbulence** → **Interaction Flame / Flow Field / Geometry** 

Laboratoty Scale  $\rightarrow$  Pilot Scale  $\rightarrow$  Industrial Scale  $\rightarrow$  Landscape Scale

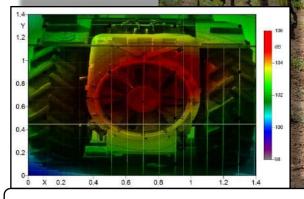
... to "REAL SCALE"



#### Consiglio Nazionale delle Ricerche Constante delle Ricerche STEMS Istituto di Scienze e Tecnologie per l'Energia e la Mobilità Sostenibili

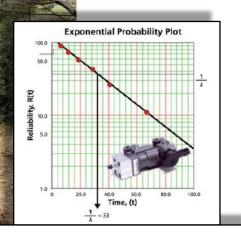
# **PROCESS, PLANT AND MACHINE SAFETY**

Develop protocols and best practices for safety in robotics, with particular attention to collaborative robotics and driving or other autonomous functions



Reduce risks and improve comfort by limiting acoustic and vibrational emissions from machinery, vehicles and their components Promote safety-driven development in the control of machines and processes

TTEYME



Develop predictive methodologies on an experimental basis for the quantification of reliability parameters and response to fault conditions

# CHALLENGES /GOALS

# CHEMICAL SAFETY

- Experimental characterization (under process conditions)
- Computational Fluid Dynamics (CFD) 3D models based on LES and URANS approaches
- Detailed kinetic modeling
- Development of predictive models for shelf-life
- Stability and biforcational analysis through multi-scale methods for complex systems

#### **MACHINERY SAFETY**

- Analysis, verification and validation of systems according to functional safety standards
- Model-based development of algorithms of control
- Statistical calculation and prediction of the reliability parameters (MTTF, B10, etc.) of the components
- System performance calculation
- Psychoacoustics for product sound quality
- Measurement and containment of acoustic and vibrational emissions

#### **RISK ASSESSMENT**

- Methods of analysis and risk reduction through optimization methods based on the theory of complex networks
- Methods based on artificial intelligence and data mining methods to identify the critical conditions for catastrophic transitions in complex systems

# SKILLS / METHODS / INSTRUMENTS

## **CHEMICAL SAFETY**

- ✓ Flammability and Explosive behavior of gases / vapors, dusts and hybrid systems (dust-gases / vapors)
- $\checkmark$  Propagation and extinguishing of industrial fires
- ✓ Fire response of materials
- ✓ Loss of control of chemical systems Runaway phenomena
- ✓ Aging of energetic materials (explosives and propellants)
- ✓ Instability of chemical processes
- ✓ Industrial toxicology

#### **MACHINERY SAFETY**

- ✓ Control strategies and systems for functional safety
- ✓ Acoustic and vibrational emissions
- ✓ Transposition and application of safety regulations

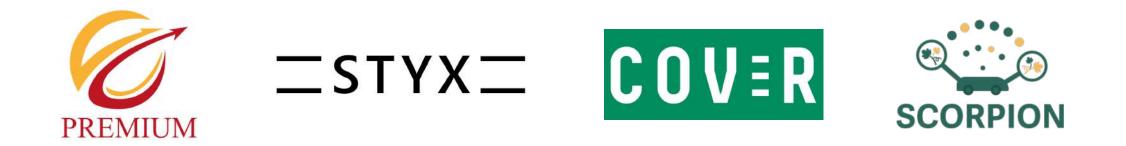
#### **RISK ASSESSMENT**

- ✓ Development of real-time simulators for the control and management of the propagation of forest fires
- ✓ Development of methodologies for the optimal placement of fuel breaks for the reduction of forest fire risk



# **P**ROGETTI **EU**

- Prediction Models for the Implementation of Munition Health Management (*PREMIUM*) European Defence Agency (EDA), 2021-2025
- Stand-off Detection of Hybrid Threats Containing Explosives (STYX) European Defence Agency (EDA), 2021-2025
- Being Safe around Collaborative and Versatile Robots in Shared Spaces (COVR) Horizon 2020, 2018-2021
- Cost Effective Robots for Smart Precision Spraying (SCORPION) Horizon 2020, 2021-2023





# **PROCESS, PLANT AND MACHINE SAFETY**



**NOVARTIS** 

































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## **I**STITUZIONI

- Institute for Systems and Computer Engineering, Technology and Science (INESC TEC) (Portogallo)
- EURECAT Technology Centre of Catalonia (Spagna)
- Loughborough University (Regno Unito)
- Laboratoire Réactions et Génie des Procédés (LRGP), Université de Lorraine, CNRS (Francia)
- Laboratoire de Recherche PRISME, Université d'Orléans, INSA Centre Val de Loire (Francia)
- French Alternative Energies and Atomic Energy Commission (CEA) (Francia)
- Roessingh Research and Development (RRD) (Paesi Bassi)
- Netherlands Organisation for Applied Scientific Research (TNO) (Paesi Bassi)
- Karlsruhe Institute of Technology (KIT) (Germania)
- Fraunhofer-Gesellschaft (Germania)
- Danish Technological Institute (DTI) (Danimarca)
- Swedish Defence Research Agency (FOI) (Svezia)
- Warsaw University of Technology (WUT) (Polonia)
- Polish Military Institute of Armament Technology (MIAT) (Polonia)
- Polish Military University of Technology (MUT) (Polonia)
- Ministry of Rural Development and Food (Grecia)